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What is the final size of turbulent mixing zones driven by the Faraday instability?

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Appearing at periodically accelerated interfaces, discovered by Faraday (1831)

$$G(t) = G_0(1 + F\sin\omega t)$$



Linear analysis based on Floquet decomposition see Benjamin and Ursell (1954), Kumar and Tuckerman (1994).

A sub-harmonic response is commonly observed, corresponding to $\omega/2$ oscillations of the interface.



The Faraday problem is mostly studied in the context of laminar flows.

However, for miscible fluids, if the forcing F is strong enough or for sufficiently disordered initial conditions, standing waves interact each other leading to a turbulent mixing zone (MZ).



FIGURE 5. Image sequence of interface evolution during an experiment: (a) t=0.5(b) t = 4.98 s, (c) t = 6.32 s, (d) t = 6.74 s, (e) t = 6.98 s and (f) t = 11.68 s. Experimental parameters: A = 10 cm, f = 1.5 Hz and $t_0 = 75$ min.

see also Diwakar et al. PoF (2015)

As the MZ grows, resonance conditions are no longer fulfilled. This leads to a saturation of the MZ 's width together with a decay of turbulence intensity.

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What is the final size?





Neglecting the influence of initial conditions and dissipative phenomena, the only control parameters in this problem are ω , A, G_0 , F leading to :

$$L_{\mathsf{sat}} = rac{2\mathcal{A}G_0}{\omega^2}\mathcal{G}(F)$$



▶ (I) Theoretical framework

Mixing zone (MZ), stratified homogeneous turbulence (SHT) and rapid acceleration (RA) model

- (II) Gravity waves and mean density profile
 Weakly non linear analysis and derivation of a saturation criterion
- (III) Verification of the saturation criterion
 Simulations of homogeneous (SHT) and inhomogeneous (MZ) stratified
 flows



► (I) Theoretical framework

Mixing zone (MZ), stratified homogeneous turbulence (SHT) and rapid acceleration (RA) model

(I) Equations in the Boussinesq limit

Mixing Zone (MZ)



Stratified Homogeneous Turbulence (SHT)

 $\begin{array}{l} \partial_t C + (\mathbf{U} \cdot \nabla) C = \mathcal{D} \Delta C, \\ \partial_t \mathbf{U} + (\mathbf{U} \cdot \nabla) \mathbf{U} = -\nabla P + 2\mathcal{A}CG(t)\mathbf{n}_3 + \mu \Delta \mathbf{U}, \\ \nabla \cdot \mathbf{U} = 0, \\ \nabla \cdot \mathbf{U} = 0, \\ \dot{L} = \frac{12}{l} \ell_0 \langle u_3 c \rangle, \end{array}$

See Griffond et al. JFE (2014), Soulard et al. PoF (2014), Burlot et al. JFM (2015)



A simple model for vertical velocity $U(t, \theta)$ and buoyancy coefficient $\mathcal{B}(t, \theta)$ cf Gréa. PoF, (2013).

$$\begin{split} \partial_t \mathcal{U} &= -2\mathcal{A}G(t)\sin^2(\theta)\mathcal{B}, \\ \partial_t \mathcal{B} &= \frac{1}{L}\mathcal{U}, \\ \dot{L} &= \frac{12}{L}\int_0^\pi \mathcal{U}\mathcal{B}\sin(\theta)d\theta \end{split}$$

In short, this is RDT, Hanazaki & Hunt, JFM (1996) + equation for L It is convenient to write it on the form :

$$\partial_{tt}\mathcal{B}(t,\theta) + \frac{\dot{L}(t)}{L(t)}\partial_{t}\mathcal{B}(t,\theta) + \frac{2\mathcal{A}G(t)\sin^{2}(\theta)}{L(t)}\mathcal{B}(t,\theta) = 0,$$

$$L(t) = 6\int_{0}^{\pi} \mathcal{B}^{2}(t,\theta)\sin(\theta)d\theta + L_{0}.$$



(II) Gravity waves and mean density profile Weakly non linear analysis and derivation of a saturation criterion



Considering
$$B(t', heta)=\mathcal{B}(t, heta)/(6L_0)^{1/2}$$
 and $t'=N_0t$ with $N_0=(2\mathcal{A}G_0/L_0)^{1/2}$ we get :

$$\partial_{tt}B(t,\theta) - 2rac{\dot{\Omega}(t)}{\Omega(t)}\partial_t B(t,\theta) + \sin^2(\theta)\Omega^2(t)\left(1 + F\cos(\omega/N_0 t)\right)B(t,\theta) = 0,$$

 $\Omega^2(t) = rac{1}{1 + \int_0^{\pi} B^2(t,\theta)\sin(\theta)d\theta}.$

Non linear system of second order equations.

This relatively simple model describes how gravity waves interact with the mean density profile.

Linearising, we obtain for $\theta \in [0 \ \pi]$:

$$\partial_{tt}B(t,\theta) + \sin^2(\theta) \left(1 + F\cos(\omega/N_0 t)\right)B(t,\theta) = 0.$$

A Mathieu equation for each angle θ which stability is expressed in the phase diagram. Studied by Benielli and Sommeria JFM 1998 (Merci Benjamin !)

(II) Mechanism in the stability diagram



Frequencies of gravity waves

$$\sin(\theta) \left(\frac{2\mathcal{A}G_0}{L}\right)^{1/2}$$

Idea : Saturation if all the gravity waves are stable?



$$\begin{split} \partial_{tt}B(t,\theta) &- 2\frac{\dot{\Omega}(t)}{\Omega(t)}\partial_{t}B(t,\theta) + \sin^{2}(\theta)\Omega^{2}(t)\left(1 + F\cos(\omega/N_{0}t)\right)B(t,\theta) = 0,\\ \Omega^{2}(t) &= \frac{1}{1 + \int_{0}^{\pi}B^{2}(t,\theta)\sin(\theta)d\theta}. \end{split}$$

Same expansion for B:

$$B(t,\theta) = \varepsilon \left(B^{(0)}(t,\tau,\theta) + \varepsilon B^{(1)}(t,\tau,\theta) + \varepsilon^2 B^{(2)}(t,\tau,\theta) + \varepsilon^3 B^{(3)}(t,\tau,\theta) + \ldots \right),$$

with $\tau = \varepsilon^2 t$ (we use steepest descent method to approximate integrals).

We assume further see Godreche & Manneville (2005)

$$N_0^2/\omega^2 - 1/4 = \varepsilon^2 \Delta$$
 & $F = \varepsilon^2 f$

Close to first resonance condition with small forcing

(II) Multiple-scale analysis

At leading order

$$\begin{aligned} \partial_{tt}B^{(0)}(t,\tau,\theta) + \sin^2(\theta)B^{(0)}(t,\tau,\theta) &= 0, \text{ at order } \varepsilon, \\ \partial_{tt}B^{(1)}(t,\tau,\theta) + \sin^2(\theta)B^{(1)}(t,\tau,\theta) &= 0, \text{ at order } \varepsilon^2. \end{aligned}$$

General solution on the form :

$$B^{(0)}(t,\tau,\theta) = a(\tau,\theta)e^{i\sin(\theta)t} + a^*(\tau,\theta)e^{-i\sin(\theta)t},$$

$$B^{(1)}(t,\tau,\theta) = b(\tau,\theta)e^{i\sin(\theta)t} + b^*(\tau,\theta)e^{-i\sin(\theta)t}.$$

At order ε^3

$$\partial_{tt}B^{(2)} + \sin^2(\theta)B^{(2)} = -2\partial_{t\tau}B^{(0)} + 2\sin^2\theta B^{(0)}\Lambda(\tau) - f\sin^2\theta B^{(0)}\sin(\omega/N_0t)$$
 focusing on $\theta = \pi/2$:

$$-2i\partial_{ au}a(au)+2a(au)\Lambda(au)-rac{1}{2}fa^{*}(au)e^{-4i\Delta au}=0$$

...with stationary solutions corresponding to

$$\frac{L_{\mathsf{sat}}}{L_0} = \frac{N_0^2}{\omega^2} (2F + 4)$$



We have just demonstrated that for $F\ll 1$ and close to the first resonance condition that :

$$L_{
m sat} = rac{2 \mathcal{A} G_0}{\omega^2} (2F+4) pprox rac{2 \mathcal{A} G_0}{\omega^2} \mathcal{G}(F)$$

where \mathcal{G} corresponds to the first transition curve in the Mathieu stability diagram. Is this result more general?



(III) Verification of the saturation criterion Simulations of homogeneous (SHT) and inhomogeneous (MZ) stratified flows









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(III) Phase diagram for SHT and MZ simulations



Relatively weak influence of the initial Froude number.

Instability triggered for F > 0.2 - 0.3 due to eddy viscosity? (see also Falcon et al. PRE 2009)



- An weakly non-linear analysis of the mechanism describing interactions between gravity waves and mean density profile is performed.
- > We derive a saturation criterion for final states of MZ driven by the Faraday instability.
- ▶ The prediction for *Ls* is verified against more than 300 MZ and SHT simulations.
- We identify harmonic/ sub-harmonic transition.
- Experimental verifications?

Paper submitted to JFM

Thank you