

Influence of liquid and gas properties on impact pressures for a rectangular liquid patch impact

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Outline

- Test case description
- Numerical model
- Flow description
- Influence of physical properties on maximal pressure
- Energy considerations
- Conclusions and perspectives





- Systematic study
 - Geometrical properties



Length	(m)
Н	15
h	8
h ₁	2
h ₂	5
L	20
I	10
l ₁	5







Systematic study Physical characteristics





Mathematical model

Euler equations for compressible fluids

Conservation laws

Mass conservation: Momentum conservation:

$$\mathcal{L}_{\boldsymbol{v}^{o}}(\rho) + \operatorname{div}\left(\rho(\boldsymbol{v} - \boldsymbol{v}^{o})\right) = 0$$

$$\mathcal{L}_{\boldsymbol{v}^{o}}(\rho\boldsymbol{v}) + \operatorname{div}(\rho\boldsymbol{v}\otimes(\boldsymbol{v} - \boldsymbol{v}^{o}) + p\mathbb{I}) = S$$

Impact : no viscosity (compressible Euler equations) Impact : Isentropic assumption (energy equation not coupled)

• Equations of state

Gases: classical Laplace equation Liquids: isentropic stiffened gas EoS

$$p = \frac{\rho_0 a_0^2}{\gamma} \left(\left(\frac{\rho}{\rho_0} \right)^{\gamma} - 1 \right)$$

▶ ALE formulation

Point motion: Volume evolution:

$$\frac{\frac{d\boldsymbol{x}}{dt} = \boldsymbol{v}^o}{\frac{dw}{dt} = w \text{div}(\boldsymbol{v}^o)$$

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ALE transport operator:

$$\mathcal{L}_{v^o}(f) = \frac{\partial f}{\partial t} + \operatorname{div}(f \boldsymbol{v}^o)$$

Numerical model

Smoothed Particle Hydrodynamics

Particle approximation

$$\Pi^{h}(f)(x) = f * W(x) = \int_{\mathbb{R}^{d}} f(y)W(x - y, h)dy$$

Conservation laws

$$\frac{d}{dt}(w_i\phi_i) + w_i\sum_j w_j(F_i + F_j).\nabla W_{ij} = w_iS_i$$

Discrete scheme equivalent to Finite Volume schemes Upwind with Riemann solver Higher order scheme with MUSCL reconstruction

Lagrangian evolution

$$\frac{d\boldsymbol{x}_{i}}{dt} = \boldsymbol{v}_{i}$$

$$\frac{dw_{i}}{dt} = w_{i} \sum_{j} (\boldsymbol{v}_{j} - \boldsymbol{v}_{i}) \cdot \nabla W_{ij}$$
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Flow description



Before impact

- Liquid acceleration
- Progressive deformation of free surface
- Gas escape
- Gas pocket formation
- Free surface instabilities

During impact

- Compression of gas pocket
- oscillations of gas pocket

Flow description



Before impact

• Pressure almost 0

During impact

- Compression of gas pocket
- Pressure oscillations inside gas pocket and liquid



Flow description

Is there always a gas pocket?



Projection t=0.45s



- Boundary conditions for gas
 - u = 0 m/s on x=0
 - p = Patm on 'outlet' (gas free to escape)
- Gas pocket entrapment due to BC
 - Size of the gas pocket influenced by gas properties (DR, Mach)
 - Mix of ELP3 (pure gas compression) and ELP1 (pure liquid acoustic wave)





Influence of physical properties on maximal pressure



Particle size sensitivity study

Convergence study for $S_g=1$









 $P_{max} \rightarrow P_{ac}$ as DR $\rightarrow 0$ (no matter a0g)

P_{max} ∖ as DR *¬*

 $P_{max} \rightarrow P_{ac}$ as a0g \rightarrow 0 (to be confirmed)

Lowest P_{max} influenced by a0l (ELP1/ELP3 coupling)

Comparison with Flux-IC results (2009)



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Pmax with constant DR (density ratio)



• Pure ELP1 regime

Pmax is lowered compared to acoustic Press.

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Energy transfers



Energy transfer

Phase 1: incompressible gas escape

- <u>No gas internal</u> energy var.
- Dominated by mech. energy transfer
- Incompressible phase
- Influence of DR only

Phase 2: compressible gas escape

- Internal & mech. Gas energy var.
- Compressible phase
- Competition between gas escape and compression
- Influence of a_{0g} at escape (Mach_g)

Phase 3: compressible gas pocket

- Internal & mech. Gas energy var.
- Internal Liquid energy var.
- Compressible phase



Energy transfer

Phase 1: influence of density ratio





- DR increases mech. energy transfers between liquid and gas
- DR decreases the liquid kinematic energy: impact velocity is lowered
- DR decreases the P_{max}

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Energy transfer

Phase 2: influence of gas speed of sound



- a_{0g} decreases transfer of liquid mech. energy to gas internal energy
- Increase of gas 'spring' stiffness: more difficult to provide energy to the gas
- a_{0g} decreases the P_{max}

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Global overview



Conclusions

Small gas stiffness

- convergence of P_{max} towards liquid acoustic pressure
- Verified if DR \rightarrow 0, or $a_{0G} \rightarrow 0$

Large gas stiffness through DR increase

- Strong influence of DR during main part of gas escape
- Increase of gas pocket size
- Increase of gas stiffness
- Double influence to lower impact pressure

Large gas stiffness through a_{0G} increase

- Increase of gas compressibility only
- Small influence on gas escape
- Less efficient than increase in DR, to reduce impact pressures

Liquid stiffness

- Small liquid stiffness: convergence of P_{max} towards liquid acoustic pressure (ELP1)
- Large liquid stiffness: increase of coupling between liquid and gas stiffness (Paradox!)



Perspectives

Gas escape phase

- Understand the energy transfers due to DR, a_{0G}
- Influence of gas Mach number on gas escape
- Is it possible to predict the gas pocket size?
- Is it possible to divide the flow into incompressible and compressible phases
- Influence of gas on free surface shape for more general liquid shapes



Thank you for your attention

